

THE MODEL OF TEMPORARY TEMPERATURE FIELD DURING MULTI-PASS ARC WELD SURFACING. PART I: ANALYTICAL DESCRIPTION

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Abstract. This work presents a model of a temperature field in a steel element during multi-pass Gas Metal Arc Weld surfacing taking into account heat of the melted electrode material. An analytical solution for a half-infinite body model is obtained by aggregating temperature increments caused by applying liquid metal and heat radiation of a moving electrode. The assumptions are Gaussian distributed heat sources of applied melted electrode material and of an electric arc.

Keywords: *temperature field, Gas Metal Arc Weld surfacing, modelling*

1. Introduction

The basis for welding processes and laser heat processing is the usage of a concentrated moving heat source, which causes temperature field to be changed in time and space. Two approaches dominate in temperature field modeling of these processes. The first approach is numerical, in which the finite difference methods, infinitesimal heat balances and FEM are commonly used [1-7]. The second approach consists of an analytical solution, described further in this work, in which integral transformations and the Green's function method are used frequently. With regard to the common multiple-welding, temperature field models are based on the finite element method [8-13], however, there is lack of analytical solutions.

Modeling of temperature field caused by moving heat source (during welding) was initiated in the middle of the last century by Rosenthal's [14] and Rykalin's [15] works, which assumed point and linear model of heat source. Eagar and Tsai [16] modified Rosenthal's model including 2D Gaussian distributed heat source and developed the solution to a travelling heat source in a semi-infinite steel plate. The model of double ellipsoidal, three-dimensional heat source was first introduced by Goldak et al. [1]. Since then many researchers have tried to determine the temperature field closest to real distribution using analytical methods [17-21].

Analytical solution to heat conduction equation offers a quick assessment of temperature field and its dependence on parameters such as e.g. heat source velocity and its power. This method is still very popular in the description of a temperature field.

In most cases of existing solutions of the temperature field only direct effects of electric arc heat on the material of welded or surfaced object are taken into account. Part of the heat generated by the electric arc is consumed to melt the electrode or the additional material, and then transferred to the welded object. The division of the whole heat generated by the electric arc in the modelling of the temperature field is encountered in the literature. Wu and Sun [22] for large deformations of the weld pool and the weld itself have suggested a model based on the bimodal heat distribution of an electric arc in GMA (Gas Metal Arc) welding. Jeong and Cho [23] have proposed taking into account the area of melted metal in fillet weld by summing up bivariate Gaussian distributed heat source. Analogically, Kang and Cho [24] solved the temperature field in the welding model using the GTA (Gas Tungsten Arc) method taking into consideration filler wire. In solution, the total amount of heat supplied to the base material is specified by adding up the heat of electric arc in the form of flat Gaussian source and point heat source of melted filler wire.

Surfacing by welding is distinguished by applying liquid metal (in some cases up to 20 millimeters thick), which spills across the surface and constitutes additional heat source. Analyses of metallographic specimens of surfaced elements [25] indicate that fusion lines have more irregular shapes than in the case of welding due to liquid metal spilling across the surface of welded element. The necessity of taking into consideration the heat of melted metal in temperature field solutions in welding processes is therefore essential, which is presented in this work.

2. The analytical description of the temperature field during multi-pass surfacing

The proposed model assumes physically one heat source - an electric arc, and the heat transfer to the surfaced object is divided into the heat transferred directly through the electric arc and through the melted material of electrode in the form of drops that under the influence of electromagnetic forces are detached and transferred to the forming weld. This material, after mixing in the weld pool, along with the melted material of the object, constitutes the weld. It is assumed that the volume of weld reinforcement is approximately equal to the volume of melted electrode wire, and the amount of heat consumed for melting the electrode equal for the amount of heat accumulated in the reinforcement of the weld pad. It allows the formulation of the temperature field formula:

$$T(x, y, z, t) - T_0 = \Delta T_d(x, y, z, t) + \Delta T_w(x, y, z, t), \quad (1)$$

where $\Delta T_a(x,y,z,t)$ and $\Delta T_w(x,y,z,t)$ are temperature accruals caused by the direct impact of electric arc heat and the heat of weld reinforcement (used for fusion of electrode) respectively.

Based on the solution of temperature field for the following heat sources: point [26], surface [27] and volumetric [28], temperature field during single pass surfacing is described [29], where numerical simulation results are confirmed experimentally by other authors [25] (Fig. 1).

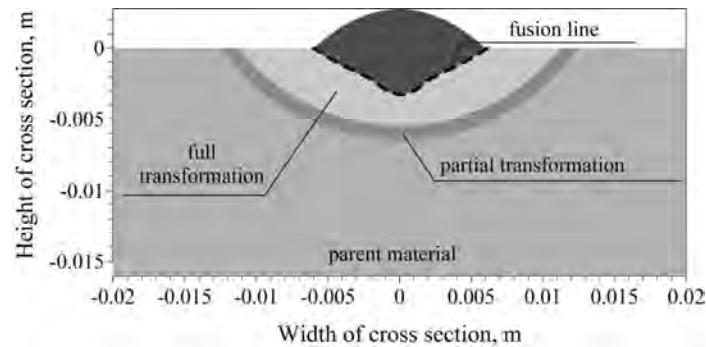


Fig. 1. Heat affected zone: dashed line - fusion line obtained experimentally

In the modelling of temperature field during multi-pass surfacing by welding, one has to take into account changes of temperature caused by the application of consecutive welds (temperature increases with successive passages of the electrode as well as the cooling of already applied welds and areas previously heated), including the overlapping of melted areas (overlaps). Then the temperature field during the application of the k -th weld is described by the relationship (Fig. 2):

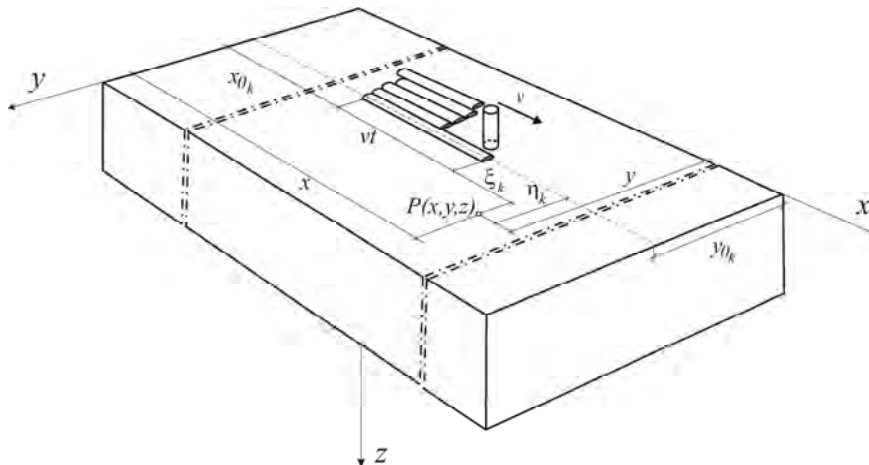


Fig. 2. Scheme for determining temporary distance between the selected point of object and heat source

$$T(x, y, z, t) - T_0 = \sum_{j=1}^{k-1} \Delta T_j^C + \Delta T_k^H, \quad (2)$$

where ΔT_j^C denotes temperature increase caused by already applied (cooling down) j -th weld, while ΔT_j^H temperature increase during application of the k -th weld. In contrast, the temperature field after application of all welds is equal to:

$$T(x, y, z, t) - T_0 = \sum_{j=1}^k \Delta T_j^C, \quad (3)$$

where:

$$\Delta T_k^H = \sum_{i=1}^2 A_i^H \int_{t_{bk}}^t F_i^H(t'') dt'', \quad (4)$$

$$\Delta T_j^C = \sum_{i=1}^2 A_i^C \int_{t_{bj}}^{t_{ej}} F_i^C(t') dt', \quad (5)$$

(index $i = 1$ refers to temperature increase caused by the heat transferred to the weld through droplets of melted electrode material, while $i = 2$ refers to temperature increase caused by direct radiation of the electric arc),

$$A_i^H = \frac{3}{8} \frac{\dot{q}_i}{C_p \rho \pi a z_{0i}} \exp\left(-\frac{v\xi}{2a} - \frac{v^2 t_{0i}}{4a}\right), \quad (6)$$

$$F_H(t'') = \frac{1}{t'' + t_{0i}} \exp\left(-\frac{\xi_k^2 + \eta_k^2}{4a(t'' + t_{0i})} - \frac{v^2 t''}{4a}\right) \left\{ \left(1 - \frac{z^2 + 2at''}{z_{0i}^2}\right) \operatorname{erf}\left(\frac{z + z_{0i}}{2(at'')^{0.5}} - \Phi(z) \operatorname{erf}\left(\Phi(z) \frac{z - z_{0i}}{2(at'')^{0.5}}\right)\right) + \frac{4at''}{z_{0i}^2} \left(\frac{z + z_{0i}}{(4\pi at'')^{0.5}} \exp\left(-\frac{(z - z_{0i})^2}{4at''}\right) - \frac{z - z_{0i}}{(4\pi at'')^{0.5}} \exp\left(-\frac{(z + z_{0i})^2}{4at''}\right) \right) \right\} \quad (7)$$

$$A_i^C = \frac{3\dot{q}_i}{8C_p \rho \pi a z_{0i}}, \quad (8)$$

$$\Phi(z) = \begin{cases} -1 & \text{for } z \in \langle 0, z_{0i} \rangle \\ 1 & \text{for } z \in (z_{0i}, \infty) \end{cases}, \quad (9)$$

$$F_C(t') = \frac{1}{t + t_{0i} - t'} \exp\left(-\frac{(x - vt' - x_0)^2 + (y - y_0)^2}{4a(t + t_{0i} - t')}\right) \left\{ \left(1 - \frac{z^2 + 2a(t-t')}{z_{0i}^2}\right) \left(\operatorname{erf}\left(\frac{z + z_{0i}}{2(a(t-t'))^{0.5}}\right) - \Phi(z) \operatorname{erf}\left(\Phi(z) \frac{z - z_{0i}}{2(a(t-t'))^{0.5}}\right) \right) + \frac{4a(t-t')}{z_{0i}^2} \left(\frac{z + z_{0i}}{(4\pi a(t-t'))^{0.5}} \exp\left(-\frac{(z - z_{0i})^2}{4a(t-t')}\right) - \frac{z - z_{0i}}{(4\pi a(t-t'))^{0.5}} \exp\left(-\frac{(z + z_{0i})^2}{4a(t-t')}\right) \right) \right\} \quad (10)$$

$$\xi_k = x - v \left(t - (k-1) \left(\frac{l_k}{v} + t_{pk} \right) \right) - x_{0k1}, \quad (11)$$

$$\eta_k = y - y_{0k}, \quad (12)$$

$$\dot{q}_2 = \kappa UI - \dot{q}_1, \quad (13)$$

a - thermal diffusivity [m^2/s], C_p - specific heat [$\text{J}/\text{kg K}$], ρ - density [kg/m^3], z_{0i} [m] denotes depth of heat source deposition, y_{0k} - coordinate of k -th weld axis, quantity t_{0i} [s] characterizes the surface heat distribution, so that:

$$r_i^2 = 4at_{0i}, \quad (14)$$

where r_i denotes averaged radius of Gaussian distributed heat source [30], U [V], I [A] and κ are voltage, amperage and arc efficiency respectively, v [m/s] - welding velocity (of electrode); while t_{bj} [s] and t_{ej} [s] - denote starting and finishing time of applying the j -th weld defined as:

$$t_{bj} = (j-1) \left(\frac{l_j}{v} + t_{pj} \right), \quad (15)$$

$$t_{ej} = (j-1) t_{pj} + j l_j / v, \quad (16)$$

l_j [m] - the length of the j -th weld with coordinates x_{0j} and x_{kj}

$$l_j = x_{kj} - x_{0j}, \quad (17)$$

t_{pi} [s] - auxiliary and complementary time associated with idle motion of electrode or with other operations resulting from the needs of manufacturing process (e.g. correction or change of technological parameters) prior to application of the j -th weld.

The total amount of heat q_1 contained in the material of melted electrode is expressed by relationship [31]:

$$q_1 = \Delta q_{solid} + \Delta q_f + \Delta q_{liquid}, \quad (18)$$

where Δq_{solid} - the heat necessary to heat up the electrode from initial temperature to melting temperature:

$$\Delta q_{solid} = mC_p(T_S - T_e), \quad (19)$$

Δq_f - heat used for melting the electrode (heat of fusion):

$$\Delta q_f = mL, \quad (20)$$

Δq_{liquid} - heat used for heating up melted material to the temperature, in which the drop of metal falls on the surface of welded material:

$$\Delta q_{liquid} = mC_p(T_L - T_S). \quad (21)$$

Then Eq. (18) takes the form:

$$q_1 = mC_p(T_S - T_e) + mC_p(T_L - T_S) + mL, \quad (22)$$

where: T_e - the initial temperature of electrode (the temperature of the contact tip with the welding head) [31].

Thus, differentiating the equation (22) with respect to time, \dot{q}_1 appearing in equations (6) and (8), is defined by the relationship:

$$\dot{q}_1 = \dot{m}(C_p(T_L - T_e) + L), \quad (23)$$

where \dot{m} and m occurring in equations (19)-(23) are equal:

$$\dot{m} = \rho_e \frac{\pi d^2}{4} v_e, \quad (24)$$

v_e [m/s] - velocity of passing electrode wire with diameter d [m], density ρ_e [kg/m³], T_L [K] - temperature at which metal leaves the wire tip, L [J/kg] - latent heat of fusion and T_S [K] - solidus temperature.

3. Conclusions

Arc weld surfacing is distinguished by the application of liquid metal, which spills across the surface and creates additional heat source. Consideration of this heat source is therefore essential in temperature field solutions. In this work a temperature field description of multi-pass surfacing for half-infinite body model is presented. Point of departure for the description of this model is the solution of heat conduction equation for a single weld. In the proposed model the heat of an electric arc transferred to surfaced object is divided into the heat conducted

directly through thermal radiation from a moving electrode and the heat of melted material of the electrode in the form of drops which under the influence of electromagnetic forces are detached and fall on the weld. As a comparative criterion of numerical simulations of single-pass surfacing and experimental research, results are assumed the shape and measurements of the fusion line. The accuracy of solution is confirmed by comparison of the calculated fusion line with that obtained experimentally by other authors with the same technological parameters of the process.

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